

This Page Is Inserted by IFW Operations
and is not a part of the Official Record

BEST AVAILABLE IMAGES

Defective images within this document are accurate representations of the original documents submitted by the applicant.

Defects in the images may include (but are not limited to):

- BLACK BORDERS
- TEXT CUT OFF AT TOP, BOTTOM OR SIDES
- FADED TEXT
- ILLEGIBLE TEXT
- SKEWED/SLANTED IMAGES
- COLORED PHOTOS
- BLACK OR VERY BLACK AND WHITE DARK PHOTOS
- GRAY SCALE DOCUMENTS

IMAGES ARE BEST AVAILABLE COPY.

**As rescanning documents *will not* correct images,
please do not report the images to the
Image Problems Mailbox.**



INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

<p>(51) International Patent Classification ⁶ : G01N 21/88</p>	<p>A1</p>	<p>(11) International Publication Number: WO 99/38002</p> <p>(43) International Publication Date: 29 July 1999 (29.07.99)</p>
<p>(21) International Application Number: PCT/US99/01107</p> <p>(22) International Filing Date: 19 January 1999 (19.01.99)</p> <p>(30) Priority Data: 09/010,570 22 January 1998 (22.01.98) US</p> <p>(71) Applicant: APPLIED MATERIALS, INC. [US/US]; 3050 Bowers Avenue, Santa Clara, CA 95054 (US).</p> <p>(72) Inventors: ELYASAF, Emanuel; Tzaidi Street 9, 76305 Rehovot (IL). TIROSH, Ehud; Moshe Schorr Street 1, 97232 Jerusalem (IL).</p> <p>(74) Agents: BERNADICOU, Michael, A. et al.; Blakely, Sokoloff, Taylor & Zafman LLP, 7th floor, 12400 Wilshire Boulevard, Los Angeles, CA 90025 (US).</p>		<p>(81) Designated States: JP, KR, SG, European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE).</p> <p>Published <i>With international search report.</i> <i>Before the expiration of the time limit for amending the claims and to be republished in the event of the receipt of amendments.</i></p>
<p>(54) Title: OPTICAL INSPECTION METHOD AND APPARATUS</p> <p>(57) Abstract</p> <p>A method and an apparatus for an optical inspection of an object (12), having upper (12A) and lower (12B) faces, so as to detect defects existing on the object. First and second beams (118A, 130A) of an incident radiation are produced and directed onto the object. A light component (140) of the first incident beam, which is reflected from one face of the object, and a light component (142) of the second incident beam, which is transmitted through the upper and lower faces of the object, are simultaneously sensed. First and second images, formed, respectively by reflected and transmitted light components are acquired and analyzed so as to provide data indicative of the defects.</p> <div data-bbox="836 1113 1388 1942"> </div>		

FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AL	Albania	ES	Spain	LS	Lesotho	SI	Slovenia
AM	Armenia	FI	Finland	LT	Lithuania	SK	Slovakia
AT	Austria	FR	France	LU	Luxembourg	SN	Senegal
AU	Australia	GA	Gabon	LV	Latvia	SZ	Swaziland
AZ	Azerbaijan	GB	United Kingdom	MC	Monaco	TD	Chad
BA	Bosnia and Herzegovina	GE	Georgia	MD	Republic of Moldova	TG	Togo
BB	Barbados	GH	Ghana	MG	Madagascar	TJ	Tajikistan
BE	Belgium	GN	Guinea	MK	The former Yugoslav Republic of Macedonia	TM	Turkmenistan
BF	Burkina Faso	GR	Greece	ML	Mali	TR	Turkey
BG	Bulgaria	HU	Hungary	MN	Mongolia	TT	Trinidad and Tobago
BJ	Benin	IE	Ireland	MR	Mauritania	UA	Ukraine
BR	Brazil	IL	Israel	MW	Malawi	UG	Uganda
BY	Belarus	IS	Iceland	MX	Mexico	US	United States of America
CA	Canada	IT	Italy	NE	Niger	UZ	Uzbekistan
CF	Central African Republic	JP	Japan	NL	Netherlands	VN	Viet Nam
CG	Congo	KE	Kenya	NO	Norway	YU	Yugoslavia
CH	Switzerland	KG	Kyrgyzstan	NZ	New Zealand	ZW	Zimbabwe
CI	Côte d'Ivoire	KP	Democratic People's Republic of Korea	PL	Poland		
CM	Cameroon	KR	Republic of Korea	PT	Portugal		
CN	China	KZ	Kazakhstan	RO	Romania		
CU	Cuba	LC	Saint Lucia	RU	Russian Federation		
CZ	Czech Republic	LI	Liechtenstein	SD	Sudan		
DE	Germany	LK	Sri Lanka	SE	Sweden		
DK	Denmark	LR	Liberia	SG	Singapore		
EE	Estonia						

Optical Inspection Method and Apparatus

FIELD OF THE INVENTION

The present invention is in the field of optical inspection techniques and relates to a method and a system for inspecting patterned objects such as, for example, photomasks, printed circuit boards (PCBs) or the like.

BACKGROUND OF THE INVENTION

There is a great variety of optical inspection systems having a common goal for locating defects existing on the patterned surface of an inspected object. The term "*patterned surface*" signifies such a surface which is formed with regions having different optical properties in respect of an incident radiation.

An inspection system of the kind specified typically comprises means for illuminating an object to be inspected, acquiring images formed by light reflected from the illuminated object, and image processing. However, if the inspected object is a photomask, flexible printed circuit board (PCB) or the like, whose patterned surface typically comprises transparent and opaque regions, the acquired images formed of light reflected from the illuminated surface are not indicative of such 'defects' as foreign particles, for example, of

- 2 -

dirt or dust, which may occasionally be located in the transparent regions. Indeed, it is known that a surface of such particle is not mirror like, and, accordingly, light returned from the particle is irregularly reflected, scattered light. The problem is very essential when using the photomask as a phototool in PCB, graphic arts and printing industries.

There have recently been developed methods and systems wherein the inspection is performed by means of illuminating an object and acquiring and processing images formed of reflected and transmitted beams of light. Such systems are disclosed, for example, in U.S. Patents Nos. 5,572,598 and 5,563,702. The systems in both patents employ a so-called 'scanning technique', wherein an illuminating laser beam is generated and focused onto a pixel defining spot on the surface of an object to be inspected. The illuminated beam is deflected in an oscillatory fashion so as to sweep the spot across the inspected surface. The system is adapted for three different modes of operation. According to the first and second modes, so-called "Transmitted Light Inspection Mode" and "Reflected Light Inspection Mode", the object is point-by-point inspected by means of detecting either transmitted or reflected light, respectively. These modes of operation are timely separated. The third mode of operation, which is aimed at defects classification, is based on detecting both reflected and transmitted beams of light. A single laser beam of incident radiation is directed onto the patterned surface of an object through light deflection means and is either reflected or transmitted, or partly reflected and partly transmitted by the object. The intensity of the incident beam is determined before its interaction with the object. Two separate detectors are accommodated at opposite sides of the object and detect transmitted and reflected beams resulting from this interaction. To this end, the system comprises separate directing optics for receiving the transmitted and reflected beams, respectively, and directing them onto the detectors.

- 3 -

This approach is based on that the interaction of an incident beam with an object to be inspected causes changes in beam's intensity, which changes depend on reflectivity and transmission of the respective region of the object. Hence, by appropriately detecting the intensities of the incident beams and reflected and transmitted beams, respectively, before and after the interaction, each inspectable point, or pixel, on the surface can be represented in a so-called 'T-R space', namely by a point with coordinates corresponding to the transmitted and reflected signal values produced at that point.

However, the system requires very complicated arrangements for illuminating and collecting optics. Indeed, the illuminating arrangement should be provided with the light deflection means and detector appropriately accommodated in the optical path of the incident beam so as to determine the beam intensity prior to the interaction with the object. This complicates and extends the optical path of the incident beam. Moreover, the use of a single beam of incident radiation results in an unavoidable requirement for locating the collecting optics, as well as the detectors for sensing the reflected and transmitted beams, at opposite sides of the object.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide novel method and apparatus for automatic optical inspection of an object by means of detecting reflected and transmitted light components of an incident radiation.

There is provided, according to one aspect of the invention, a method for an optical inspection of an object, having upper and lower faces, so as to detect defects existing on the object, the method comprising the steps of:

- (a) providing first and second beams of an incident radiation;
- (b) directing the first beam of the incident radiation onto the object and

- 4 -

- sensing a light component reflected from one face of the object;
- (c) directing the second beam of the incident radiation onto the object and sensing a light component transmitted through the upper and lower faces of the object;
- (d) simultaneously acquiring first and second images of the object, wherein the first image is formed by the reflected light component and the second image is formed by the transmitted light component; and
- (e) analyzing said first and second images so as to provide data indicative of said defects.

The term "defects" used herewith signifies certain undesirable conditions of the object such as, for example, existence of foreign particles located on the object.

Thus, the idea of the present invention is based on the following main features. The first and second beams of incident radiation are produced and directed towards the object for focusing them onto the upper face. It is understood that, generally, each of the incident beams can be both reflected and transmitted by the different regions of the object. In other words, each of the incident beams, depending on the region of its interaction with the object, may be partly transmitted and partly reflected resulting in, respectively, transmitted and reflected light components. To this end, what is actually detected by two image sensors are, respectively, that light component of the first incident beam which is reflected from the object and that light component of the second incident beam which is transmitted through the object.

Generally, the first and second incident beams can be directed onto the object from the same side thereof, that is from either the upper or the lower face. In this case the sensors and associated directing optics are located at opposite sides of the object. It should be noted that it is advantageous to

- 5 -

illuminate the object from opposite faces. This enables the sensors to be placed at one side of the object and, accordingly, a common directing optics to be employed for receiving both the reflected and transmitted light components and directing them onto the respective sensors.

Thus, the reflected and transmitted light components are, preferably, directed onto the different sensors via a common optical system appropriately accommodated in the optical paths of the both light components. It is understood that, accordingly, means should be provided for successfully separating the different light components so as to be sensed by the different image sensors. To this end, two alternating embodiments of the invention are exemplified.

According to one embodiment, the first and second beams of the incident radiation are simultaneously directed onto different portions of the object. More specifically, they illuminate, respectively, first and second spaced-apart, parallel, identical strips of the upper face. The relationship between the two illuminated strips and the common optical system is such that the strips extend symmetrically relative to the optical axis of the common optical system. The optical system actually projects the strips onto the first and second image sensors, which are, preferably, line sensors. Hence, a pair of spaced, parallel lines of the object is imaged. It is understood that the dimensions of the line are defined by a field of view of the image sensor, the width a of the line being substantially smaller than that of the illuminated strip. The space between the two illuminated strips is adjusted so as to minimize an overlap region between the two images. The space d between the two imaged lines satisfies the following condition:

$$d = n \cdot a$$

wherein n is an integer such that $n \geq 1$.

According to an alternative embodiment of the invention, the first and second beams of the incident radiation illuminate the same portion of

the upper face, which portion is in the form of a strip. To this end, the first and second beams of the incident radiation are formed of light having either different wavelengths, or different polarizations. In the case of different wavelengths, the common optical system comprises a suitable beam splitter, for example, a dichroic beam splitter. In the case of the different polarizations, the common optical system is provided with appropriate beam polarizer device based, for example, on a double refraction effect.

The first and second beams of the incident radiation may be produced by either two light sources, or by a single light source adapted for generating a beam of light. If the single light source is employed, the generated beam is directed towards the object via a beam splitter, which splits it into the first and second beams of the incident radiation.

Preferably, the image sensors are of a kind adapted to receive a light signal and provide an electric output representative thereof. For example, charge coupled device (CCD) cameras, or bi-directional time delay integration (TDI) sensor may be employed.

In order to successively inspect the whole object, it is supported for sliding movement within an inspection plane along two orthogonally oriented axes. It is appreciated that in order to allow for so-called "double side" illumination, the object may be supported on a transparent slab, or, alternatively, on a frame supporting solely the periphery region of the object. As a result of the inspection, each point on the upper face of the object is represented by so-called 'reflected' and 'transmitted' images. Comparing these images to each other enables to locate the defects, if any, on the object. For that purpose, the output signals provided by the image sensors are transmitted to a processor operated by a suitable software for comparing the first and second images to each other.

According to another aspect of the present invention there is provided an apparatus for an optical inspection of an object, having upper and

lower faces, so as to detect defects existing on the object, the apparatus comprising:

- (i) an illumination system for producing first and second beams of an incident radiation and simultaneously directing them onto the object;
- (ii) a sensing system mounted for sensing a light component of the first incident beam reflected from the upper face and a light component of the second incident beam transmitted through the upper and lower faces of the object, and for providing output signals representative thereof;
- (iv) a light directing system accommodated in optical paths of the reflected and transmitted light components for directing them onto the sensing system; and
- (v) a processor coupled to the sensing system for receiving and analyzing said output signals representative of the reflected and transmitted light components and for providing data indicative of said defects.

Thus, the present invention enables to inspect an object by simultaneously illuminating it by two incident beams of light and detecting reflected and transmitted light components of these incident beams, respectively. In other words, in comparison to the above U.S. Patents, each point of the inspected object is represented by both "T-map" and "R-map", i.e. "transmitted image" and "reflected image". This simplifies the analyzing procedure. Additionally, owing to the provision of the common optical system for directing the reflected and transmitted beams onto the different sensors, and the above solutions for successful separation between the reflected and transmitted beams, the construction and operation of the apparatus can be significantly simplified.

More specifically the present invention is used for inspecting a

photomask which is typically in the form of a polished transparent substrate whose upper surface has a plurality of spaced-apart regions coated by a thin opaque layer such as, for example, chromium. The upper surface of the photomask represents a pattern in the form of transparent and opaque regions. Defects, which can be detected by the method according to the invention, may also be in the form of through-holes in the opaque regions and/or width variation of these regions. It is understood that the opaque and transparent regions of a photomask would be represented by bright and dark regions in the 'reflected image' and by dark and bright regions, respectively, in the 'transmitted image'. If a foreign particle is located in the transparent region, it will appear as a bright spot on a dark background in the reflected image and *vice versa* in the transmitted image. If a foreign particle is located in the opaque region, solely the image sensor responsive to the reflected light component will detect it. Such particle will appear as a dimmer spot on the bright background in the reflected image. The other kinds of defects such as, for example, through-holes in the opaque regions or width variation of these regions will be detected by both the reflected and transmitted beams.

BRIEF DESCRIPTION OF THE DRAWINGS

In order to understand the invention and to see how the same may be carried out in practice, several preferred embodiments will now be described, by way of non-limiting example only, with reference to the accompanying drawings, in which:

Fig. 1 is a block diagram illustrating the main components of an apparatus for optical inspection of a patterned object, according to one embodiment of the invention;

Figs. 2 and 3 more specifically illustrate the main principles of operation of the apparatus of Fig. 1;

Fig. 4 is a graphic illustration of the main principles of operation of an

optical system of the apparatus of Fig. 1;

Figs. 5a to 5f are schematic illustrations of images of the illuminated portion of an upper surface of the object during sequential steps of operation of the apparatus of Fig. 1;

Figs. 6a and 6b are schematic illustrations of two images of a region of the upper surfaces of the object; and

Fig. 7 is a block diagram illustrating the main components of an inspection apparatus, according to another embodiment of the invention; and

Fig. 8 is a block diagram illustrating the main components of an inspection apparatus, according to yet another embodiment of the invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring to Fig. 1, there is illustrated an apparatus, generally designated 10, for inspecting a photomask 12. The propagation of beams of light is shown here schematically solely in order to facilitate the understanding of the main principles of the construction of the apparatus 10. The photomask 12 is typically in the form of a polished transparent substrate having upper and lower surfaces 12a and 12b, respectively. The upper surface 12a is formed with a pattern (not shown) having a plurality of spaced-apart regions coated by a thin opaque layer such as, for example, chromium. In other words, surface 12a is formed with transparent and opaque regions. The photomask 12 is supported at its periphery region on a frame 14 mounted for sliding movement along mutually orthogonal axes x and y . Alternatively, a sliding base formed of a transparent material may be employed for the same purpose of slidingly displacing the photomask 12 within an inspection plane in a manner to provide illumination access to the lower surface 12b.

The apparatus 10 comprises an illumination assembly, generally at 16 mounted at the upper side of the photomask 12 for illuminating its upper surface 12a. The assembly 16 includes a light source 18, producing a beam of

light 18a, and an optical system 20, accommodated in the optical path of the beam 18a. The optical system 20 includes an anamorphic optics 22 typically comprising a cylindrical lens or plurality of such lenses, which are not specifically shown, a beam splitter 24 and an objective lens 26. All these components of the optical system 20 are well known *per se* and, therefore, need not be described in more detail, except to note that they enable a desired shape of the beam 18a to be obtained and focussed onto the photomask 12. As shown, the beam 18a illuminates a strip S_r of the upper surface 12a.

Further provided is an illumination assembly, generally designated 28, mounted at the lower side of the photomask 12 for illuminating its upper surface 12a. Similarly, the assembly 20 includes a light source 30 producing a beam of light 30a, and an optical system 32 accommodated in the optical path of the beam 30a. The optical system 32 comprises an anamorphic optics 34, a mirror 36 and a condenser lens 38. The beam 30a, being transmitted through the transparent lower surface 12b, illuminates a strip S_t of the upper surface 12a. It will be understood that the provision of the mirror 36 is optional and depends solely on the location of the light source 30 relative to the surface 12b.

As further schematically shown in Fig. 1 and more specifically in Fig. 2, the beam 18a impinges onto the surface 12a and is reflected from reflective regions, if any, disposed within the strip S_r , resulting in a reflected beam 40. The incident beam 30a, being transmitted through the transparent lower surface 12b of the photomask 12, impinges onto the upper surface 12a and is transmitted through transparent regions, if any, within the strip S_t , producing a transmitted beam 42.

An optical system 44, typically comprising a collecting lens or plurality of such lenses (not shown), is located at the upper side of the photomask 12 so as to be in the optical paths of both the reflected beam 40 and transmitted beam 42. The system 44 has its optical axis shown in dotted

line OA. The system 44 directs the beams 40 and 42 onto line sensors 46 and 48, respectively, thereby projecting two geometrically separated strips S_r and S_t into two imaged lines L_r and L_t . The image L_r is formed by light reflected from the strip S_r illuminated by the beam 18a, while the image L_t is formed by light transmitted through illuminated strip S_t . As more specifically illustrated in Fig. 3, in order to render the image quality at both sensors equal, the configuration is such that the illuminated strips S_r and S_t extend symmetrically relative to the optical axis OA.

It is understood, although not specifically illustrated, that the dimensions of the imaged lines L_r and L_t are defined by the field of view of each of the sensors 46 and 48 and are substantially smaller than those of the strips S_r and S_t . The sensors 46 and 48 are of a kind adapted for receiving light signals and generating electrical outputs corresponding thereto such as, for example, a conventional line-type CCD camera.

Fig. 4 illustrates the intensity distributions of the beams 40 and 42 which are in the form of two lobes 50 and 52, respectively. It is appreciated that the spacing between the two illuminated strips S_r and S_t is arranged so as to minimize an overlap region 54, thereby reducing crosstalk between the two images.

Turning back to Fig. 1, coupled to the sensors 46 and 48 is a processor 56 receiving the electrical outputs of the sensors 46 and 48. The processor 56 is operated by suitable software carrying out an image processing technique capable of analyzing the imaged lines L_r and L_t by means of comparing the electrical outputs to each other and of providing information indicative of defects, if any, on the photomask 12. The electrical outputs may also be compared with corresponding reference data which may be stored in a database of the processor 56 or derived from another photomask or from another part of the same photomask being inspected. The construction and operation of the processor 56 do not form a part of the present

invention and therefore need not be more specifically described. The information generated by the image processor 56 is output to a computer device 58 and displayed on its screen 58a.

Alternatively, although not specifically shown, the processor 56 and the computer device 58 may be combined in one integral unit. The light sources 18 and 30 may be replaced by a single light source for generating a beam of radiation, in which case the generated beam is directed onto the inspected photomask via a beam splitter so as to be split into two separate beams for illuminating the photomask from opposing sides.

The operation of the apparatus 10 will now be described with reference to Figs. 5a-5f, partly illustrating images of the upper surface 12a of the photomask 12 during the inspection. Initially, two strips are simultaneously illuminated (not shown) in the above described manner and two lines Lr_1 and Lt_1 are imaged. The lines Lr_1 and Lt_1 are identical having the same width a and length b and are aligned in a spaced-apart, parallel relationship along the y axis. A space d between the lines Lr_1 and Lt_1 is defined as follows:

$$d=na \quad (1)$$

wherein n is an integer $n \geq 1$, being equal to 1 in the present example.

At a next operational stage, the support frame 14 moves the photomask a certain preset step H_1 in a direction D_1 along the axis y , which step satisfies the following condition:

$$H_1=n_1a \quad (2)$$

wherein n_1 is an integer $n_1 \geq 1$, being equal to 1 in the present example. A further pair of lines Lr_2 and Lt_2 is imaged by the sensors 46 and 48, respectively, and corresponding electrical outputs are transmitted to the processor 56. Meanwhile, the sliding movement of the frame 14 in the direction D_1 results in a further displacement of the photomask the same step H_1 , and a pair of lines Lr_3 and Lt_3 is imaged. As clearly seen in Fig. 5c, the

lines L_{t1} and L_{r3} coincide, which means that the corresponding strip of the surface 12a has now been sequentially illuminated by the beams 30a and 18a. Figs. 5d and 5e illustrate, in a self-explanatory manner, the sequential increase of the number of such imaged lines corresponding to those strips illuminated by both beams of the incident radiation.

Hence, a slice, generally at B_i , of the surface 12a is strip-by-strip inspected by step-by-step displacing the photomask 12 in the direction D_1 along the axis y . It is understood that the beginning of the inspection is stipulated such that the lines $L_{r'}-L_{r''}$ and $L_{t'}-L_{t''}$ corresponding to those strips illuminated by either of the beams 18a or 30a, respectively, are associated with a so-called 'margin', non-patterned region of the surface 12a.

In order to inspect an adjacent slice B_{i+1} of the surface 12a, the sliding frame 14 is moved a preset step H_2 in a direction D_2 along the axis x , which step H_2 is defined as follows:

$$H_2=b \quad (3)$$

Thereafter, the photomask 12 is step-by-step displaced the same distance H_1 in a direction D_3 along the axis y . As shown, in the pair of simultaneously imaged lines L_r and L_t of the slice B_{i+1} the 'reflected' and 'transmitted' images are located in a reverse relationship relative to the direction of the displacement of the photomask, in comparison to that of the pair of simultaneously imaged lines L_{r1} and L_{t1} of the slice B_i . To this end, the image processor 56 is provided with a suitable software for controlling its operation so as to consider the respective changes in the direction of movement of the photomask 12. Additionally, although not specifically shown, optical sensors may be appropriately accommodated at either side of the frame 14.

It is important to note that if a pair of time delay integrated (TDI) sensors is employed as the imaging sensors 46 and 48, they should be of the so-called 'bi-directional' kind. The construction and operation of such a 'bi-directional' TDI sensor are well known *per se* and do not form a part of the

present invention.

Turning now to Figs. 6a and 6b, there are more specifically illustrated the imaged lines Lt_1 and Lr_3 , which correspond to the same illuminated strip on the surface 12a, which strip is sequentially illuminated by the beams 30a and 18a. It is assumed that the portion of the upper surface within the illuminated strip includes both transparent and opaque regions, generally designated 60 and 62, and that foreign particles 64 and 66 are located, respectively, in the transparent and opaque regions 60 and 62. As clearly shown, the transparent and opaque regions 62 and 64 are in the form of bright and dark areas, respectively, in the 'transmitted' image Lt_1 (Fig. 6a), while being in the form of dark and bright areas, respectively, in the 'reflected' image Lr_3 (Fig. 6b). As for the foreign particles, it is known that a surface of such particle is not mirror like, and, accordingly, light returned from the particle is irregularly reflected, scattered light. Therefore, both the transmitted and reflected beams 40 and 42 are indicative of the existence of the particle 64 located within the transparent region. The particle 64 appears as light fall-off, i.e. dark spot on the bright background 60, in the 'transmitted' image Lt_1 and as a brighter spot on the dark background 60 in the 'reflected' image Lr_3 . The existence of the particle 66 located on the opaque region 62 may be detected solely by the reflected beam 40, appearing as a dimmer spot on the bright background in the 'reflected' image Lr_3 .

It is also appreciated that, should the plane of location of the particle 64 be identified, namely the upper or the lower surface of the photomask 12, this may be achieved by slightly shifting the upper surface 12a along the axis OA, so as to be out of the focal plane, and detecting the changes in the electrical output. Additionally, it is understood, although not specifically shown, that both the 'reflected' and 'transmitted' images will be indicative of such 'defects' as through-holes in the opaque regions and missed chromium coating presenting a so-called 'width variation defect'.

During the movement of the photomask 12 along the axes y and x as described above, the processor 56, to which the electrical signals generated by the sensors 46 and 48 are continuously fed, analyzes these electric signals and produces data indicative of the condition of the photomask 12. The processed data may be in the form of a list showing in respect of each 'defect' its type and coordinates, which list is displayed on the screen 58a.

Reference is now made to Fig. 7 illustrating the main components of an apparatus, generally designated 100, which is constructed and operated according to another embodiment of the present invention. Those components which are identical in the apparatuses 10 and 100 are indicated by the same reference numbers, in order to facilitate understanding. The apparatus 100 inspects the photomask 12 supported on the sliding frame 14. Two illumination assemblies 116 and 128 are provided for illuminating the upper surface 12a of the photomask 12 from its opposite sides. The assemblies 116 and 128 are generally similar to those of the apparatus 10, each comprising a light source for emitting a beam of incident radiation and a suitable optical system accommodated in the optical path of the emitted beam. In distinction to the apparatus 10, the light sources 118 and 130 produce, respectively, light beams 118a and 130a of different wavelengths λ_1 and λ_2 . The beam 118a is directed through the optical system 20 onto the surface 12a so as to illuminate a strip S_n and be reflected from opaque regions, if any, producing a reflected beam 140. The light beam 130a, in turn, passes through the optical system 32 so as to impinge onto the surface 12a and illuminate the same strip S_n , producing a transmitted beam 142. The reflected and transmitted beams 140 and 142 are projected via an optical system 144 onto the image sensors 46 and 48, respectively. To this end, the system 144, in addition to the collecting lens 44, comprises a dichroic beam splitter 145. The dichroic beam splitter is a well known color-selective device which is widely used for

transmitting a particular band of spectral energy and reflecting any other.

It will be readily understood, although not specifically shown, that the operation of the apparatus 100 is generally similar to that of the apparatus 10. Each illuminated strip S_n is projected by the optical system 144 into two imaged lines (not shown). The photomask 12 is sequentially displaced along the axis y a certain preset step. It is appreciated that this step is, preferably, equal to the width of the imaged line so as to, on the one hand, avoid an overlap between the images and, on the other hand, speed up the inspection. Upon inspecting a slice of the photomask, the latter is displaced along the axis x a certain step which is, preferably, equal to the length of the imaged line.

Referring to Fig. 8, there is illustrated an apparatus 200 constructed and operated according to yet another embodiment of the invention. Similarly, those components which are identical in the above described embodiments and the apparatus 200 are indicated by the same reference numbers. The apparatus 200 is capable of illuminating a strip S of the upper surface 12a of the photomask 12 by two beams of incident radiation 218a and 230a having different polarizations. To this end, the optical systems 220 and 232 comprise beam polarizer devices 234 and 236 accommodated in the optical paths of the beams 218a and 230a, respectively. Alternatively, each of the light sources 218 and 230 may be of a kind adapted for producing a polarized light beam. Hence, reflected and transmitted beams 240 and 242 are of different polarizations. The dichroic beam splitter 145 of Fig. 7 is replaced by a beam polarizer device 245 of a kind capable of splitting the different polarizations. Such beam polarizer devices are known, typically comprising a polarization sensitive medium, for example, in the form of a birefringent cell or multi-layered dielectric structure. It is appreciated that light component returned from a foreign particle located in the opaque region of the upper surface of the photomask, would be, due to reflection and

- 17 -

diffraction effects, a depolarized scattered forward light. This increases the contrast of particle's appearance on the bright background in the 'reflected' image.

Those skilled in the art will readily appreciate that various modifications and changes may be applied to the preferred embodiments of the invention as hereinbefore exemplified without departing from its scope as defined in and by the appended claims. In the method claims which follow, characters which are used to designate claim steps are provided for convenience only and do not apply any particular order of performing the steps.

WHAT IS CLAIMED IS:

1. A method for optically inspecting an object having upper and lower faces for detecting defects existing on the object, the method comprising the steps of:

- a) providing first and second beams of an incident radiation;
- b) directing the first beam of the incident radiation onto the object and sensing a light component reflected from one face of the object;
- c) directing the second beam of the incident radiation onto the object and sensing a light component transmitted through the upper and lower faces of the object;
- d) simultaneously acquiring first and second images of the object, wherein the first image is formed by the reflected light component and the second image is formed by the transmitted light component; and
- e) analyzing said first and second images so as to provide data indicative of said defects.

2. The method according to Claim 1, wherein the step of acquiring the first and second images comprises directing the reflected and transmitted light components onto first and second image sensors, respectively.

3. The method according to Claim 2, wherein the first and second beams of the incident radiation are directed onto the object from the opposite faces thereof, and further comprising the step of;

directing the reflected and transmitted light components via an optical system mounted in optical paths of the reflected and transmitted light components onto the first and second image sensors accommodated at one side of the object.

4. The method according to Claim 1, wherein the steps of directing the first and second beams of the incident radiation onto the object further comprise manipulating said first and second beams of the incident radiation to

illuminate first and second parallel spaced-apart corresponding portions of the object.

5. The method according to Claim 4, wherein each of said first and second portions of the object are in the form of a strip.

6. The method according to Claim 4, wherein
the first and second beams of the incident radiation are directed onto the object from the opposite faces thereof;
the reflected and transmitted light components are directed onto, respectively, first and second image sensors, accommodated at one side of the object, via an optical system mounted in optical paths of the reflected and transmitted light components; and
the first and second portions extend symmetrically relative to an optical axis of said optical system.

7. The method according to Claim 1, wherein
the first and second beams of the incident radiation are directed onto the object from the opposite faces thereof; and
the first and second beams of the incident radiation are formed of light having different wavelengths.

8. The method according to Claim 1, wherein
the first and second beams of the incident radiation are directed onto the object from the opposite faces thereof;
the first and second beams of the incident radiation are formed of light having different polarizations.

9. The method according to Claim 4, wherein the first and second images of the first and second portions are in the form of two lines, each having a width "*a*" and a length "*b*", the width "*a*" being substantially smaller than the width of the respective portion, a space "*d*" between lines being such as to satisfy the following condition:

$$d \geq n a$$

wherein " n " is an integer such $n \geq 1$.

10. The method according to Claim 1, wherein the step of providing the first and second beams of the incident radiation comprises providing first and second light sources each generating a beam of light.

11. The method according to Claim 1, wherein the step of providing the first and second beams of the incident radiation comprises providing a light source generating a beam of light and directing the generated beam of light towards the object via a beam splitter, which splits the generated beam of light into the first and second beams of the incident radiation.

12. The method according to Claim 1, further comprising the step of:
supporting the object for sliding movement along two orthogonally oriented axes within an inspection plane so as to provide said first and second images of each point of the object.

13. The method according to Claim 1, wherein the analyzing of the first and second images comprises comparing the images to each other.

14. An apparatus for an optical inspection of an object, having upper and lower faces, so as to detect defects existing on the object, the apparatus comprising:

- i. an illumination system providing first and second beams of an incident radiation simultaneously directed onto the object;
- ii. a sensing system mounted in the vicinity of the object and simultaneously sensing a light component of the first incident beam reflected from the upper face of the object and a light component of the second incident beam transmitted through the upper and lower faces of the object and providing output signals representative thereof;
- iii. a light directing system directing the reflected and transmitted light components onto the sensing system; and
- iv. a processor coupled to the sensing system for receiving the output signals representative of the reflected and transmitted light components

and for analyzing the signals so as to provide data indicative of said defects.

15. The apparatus according to Claim 14, wherein the illumination system comprises two light sources for generating, respectively, said first and second beams of the incident radiation.

16. The apparatus according to Claim 14, wherein the illumination system comprises a light source for generating a beam of light and a beam splitter for splitting the generated beam into said first and second beams of the incident radiation.

17. The apparatus according to Claim 14, wherein the illumination system comprises a directing optics for directing the first and second beams of the incident radiation onto, respectively, the opposite faces of the object.

18. The apparatus according to Claim 14, wherein the illumination system comprises a directing optics for directing the first and second beams of the incident radiation onto, respectively, first and second parallel, spaced-apart portions of the object.

19. The apparatus according to Claim 14, wherein said first and second beams of the incident radiation are formed of light of different wavelengths.

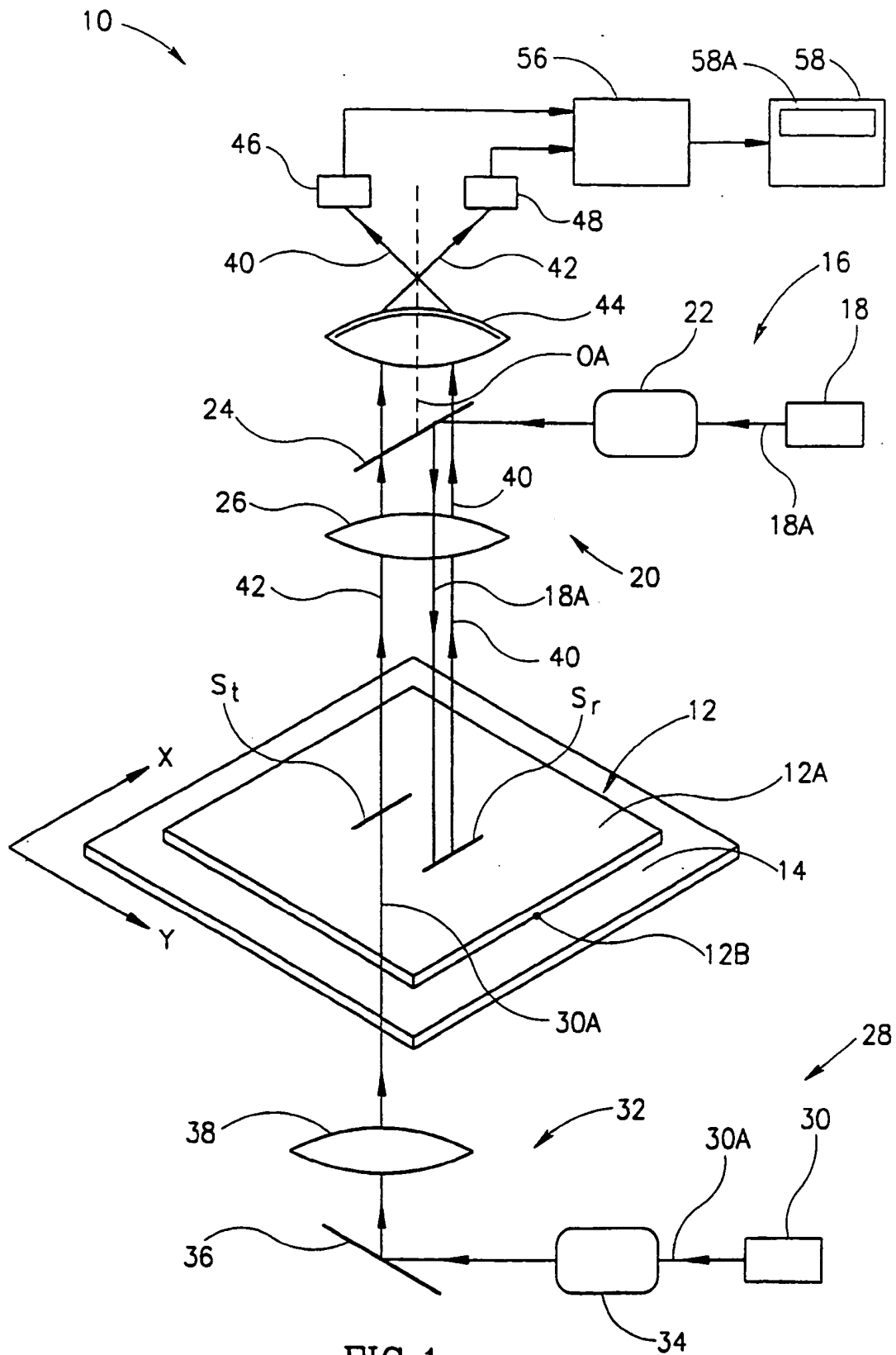
20. The apparatus according to Claim 14, wherein said first and second beams of the incident radiation are formed of light of different polarizations.

21. The apparatus according to Claim 14, wherein the sensing system comprises first and second image sensors for detecting, respectively, the reflected and transmitted light components.

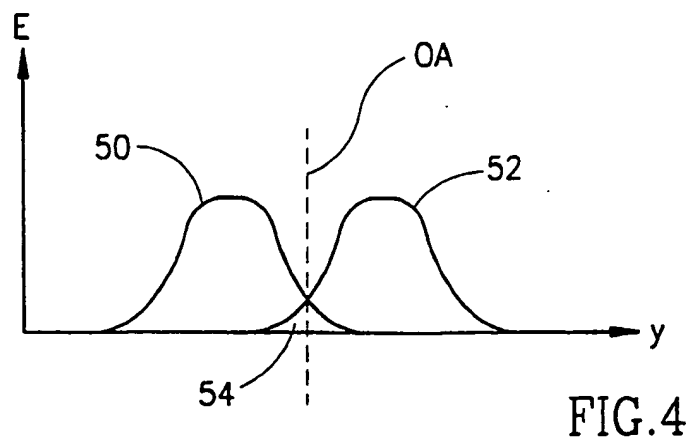
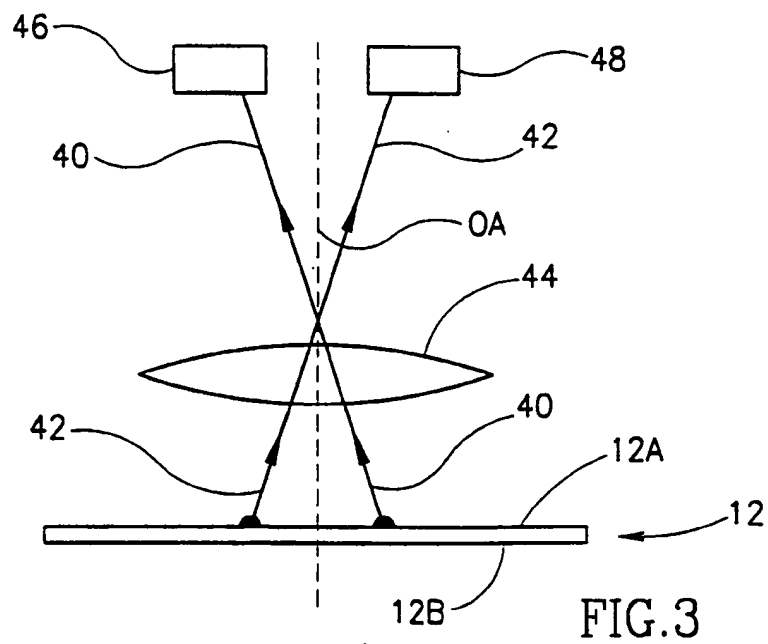
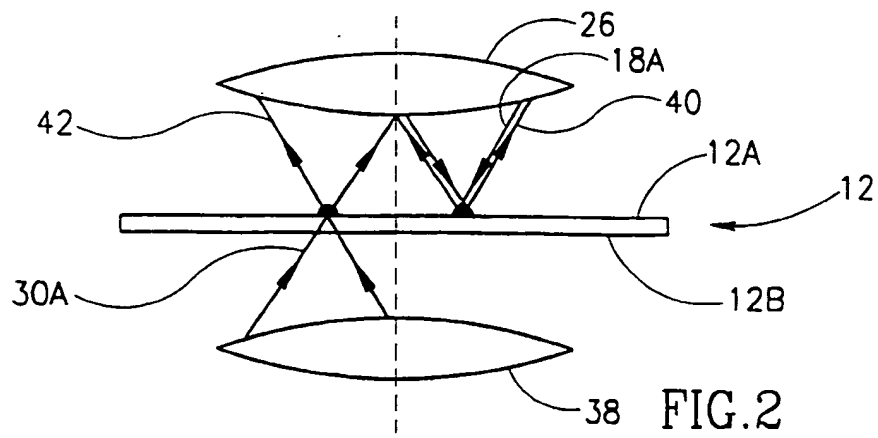
22. The apparatus according to Claim 17, wherein the light directing optics and the sensing system are accommodated at one side of the object.

23. The apparatus according to Claim 14, and also comprising a support base for supporting the object for sliding movement along two orthogonally oriented axes within an inspection plane.

1/7



2/7



3/7

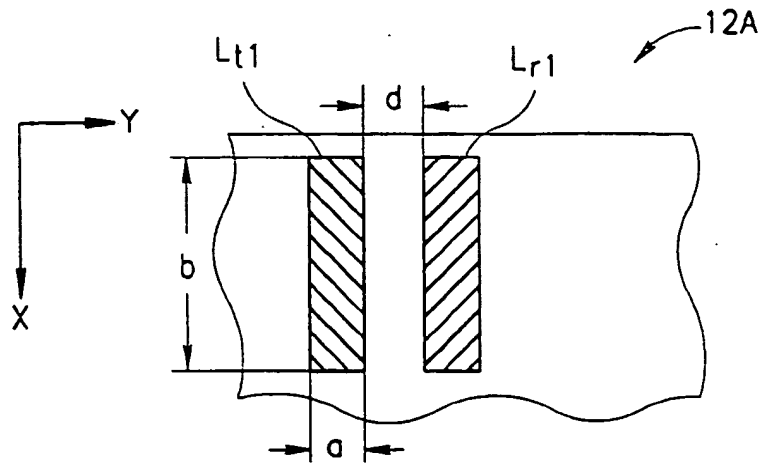


FIG. 5A

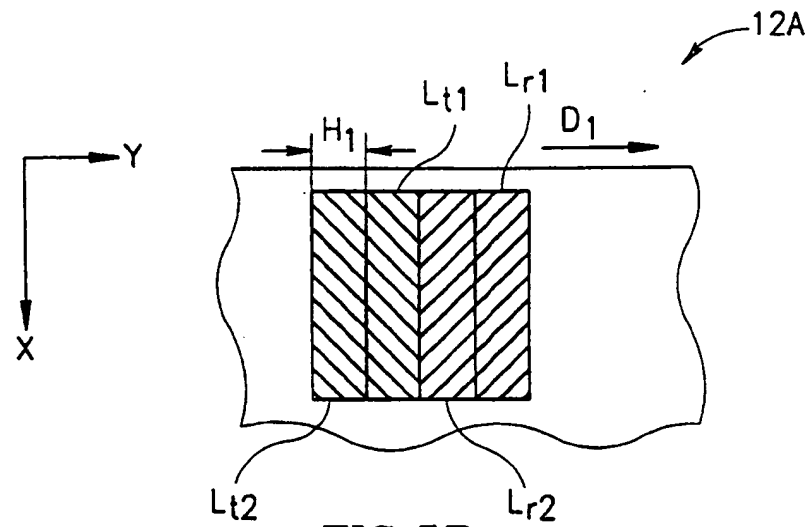


FIG. 5B

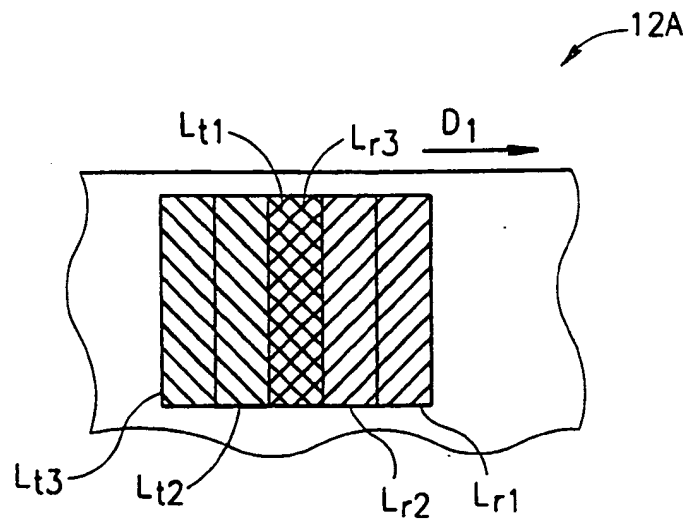
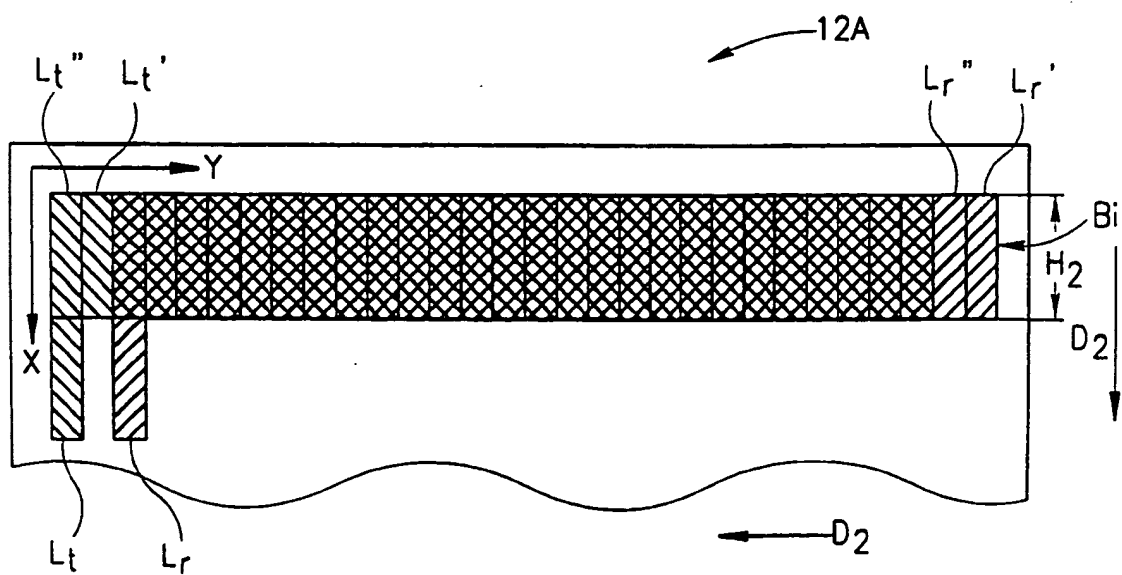
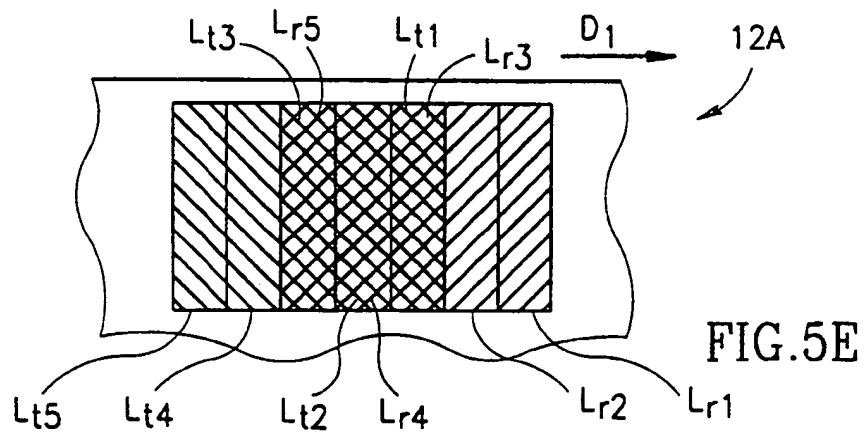
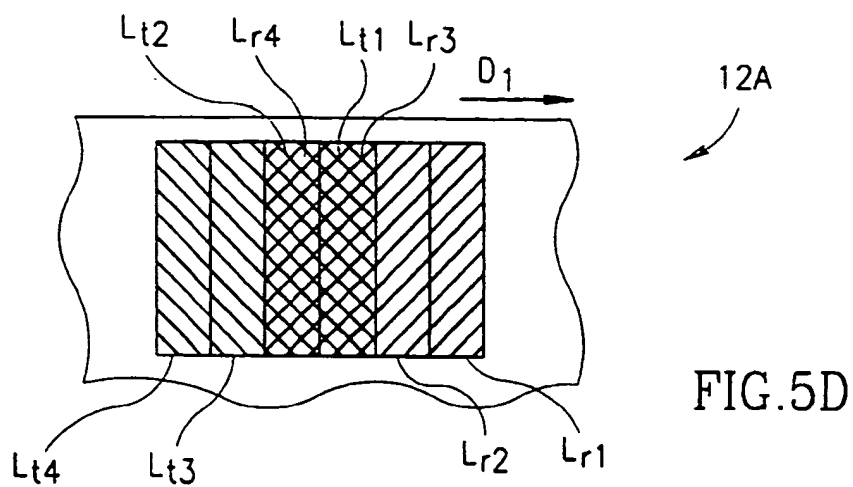


FIG. 5C

4/7



5/7

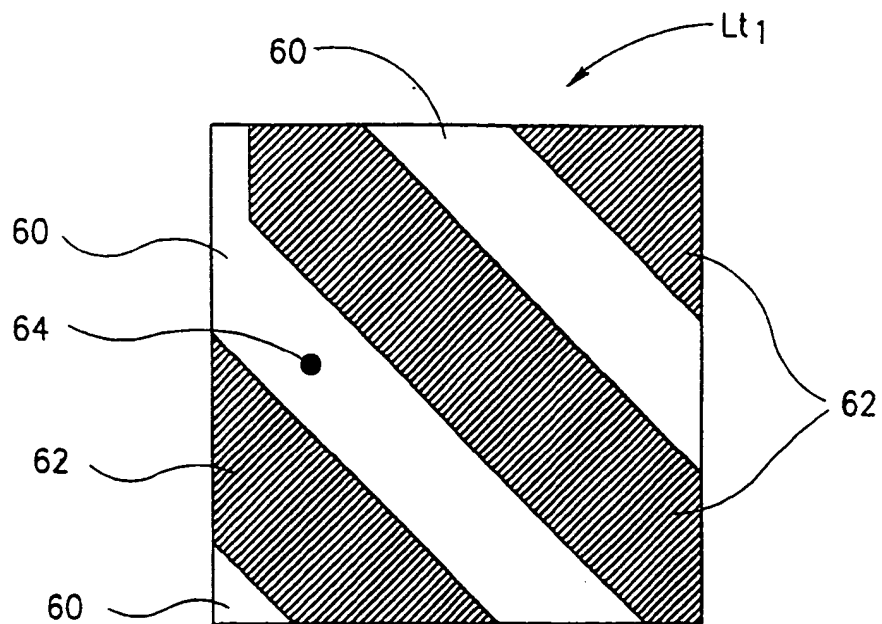


FIG. 6A

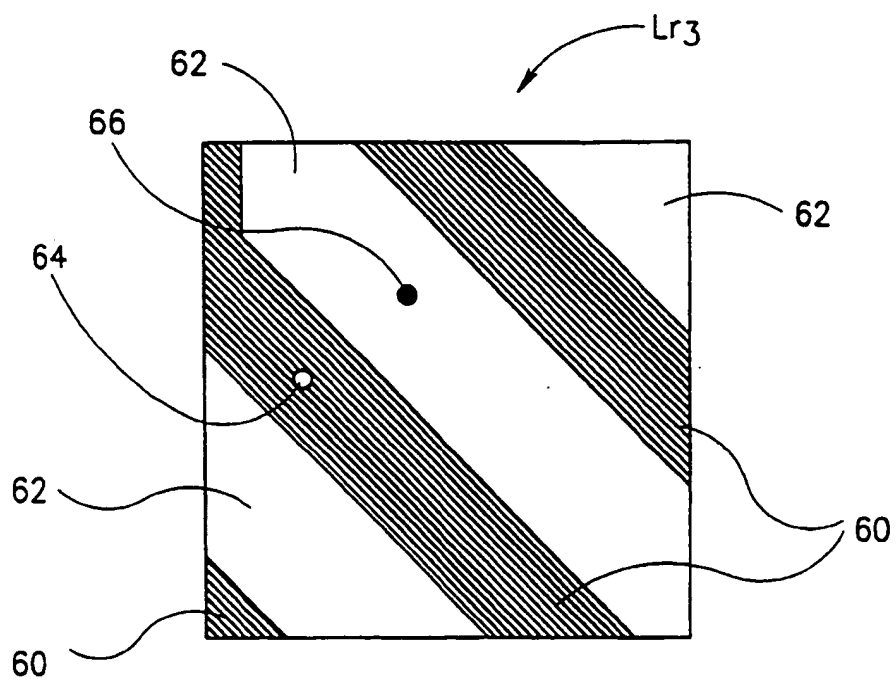


FIG. 6B

6/7

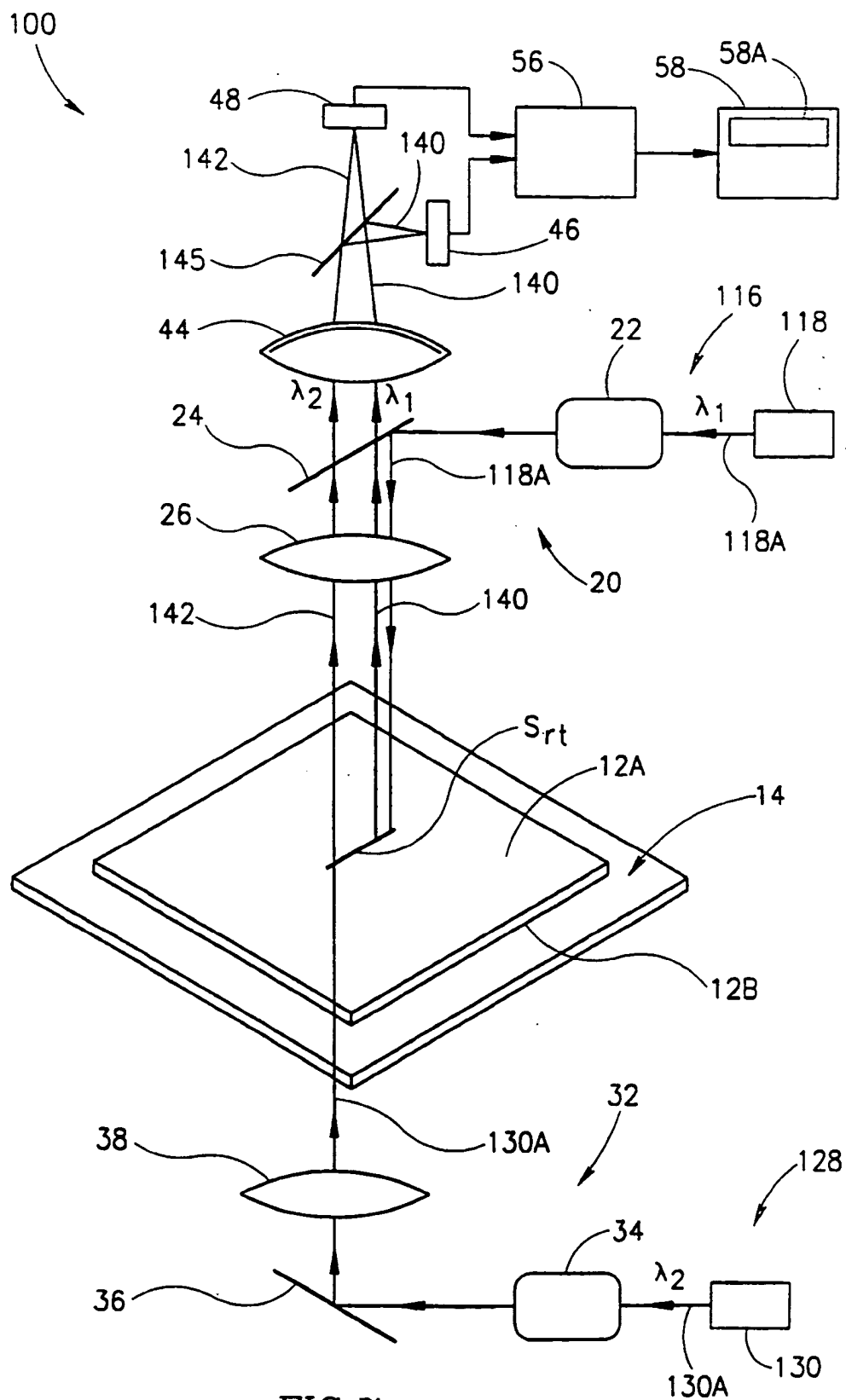
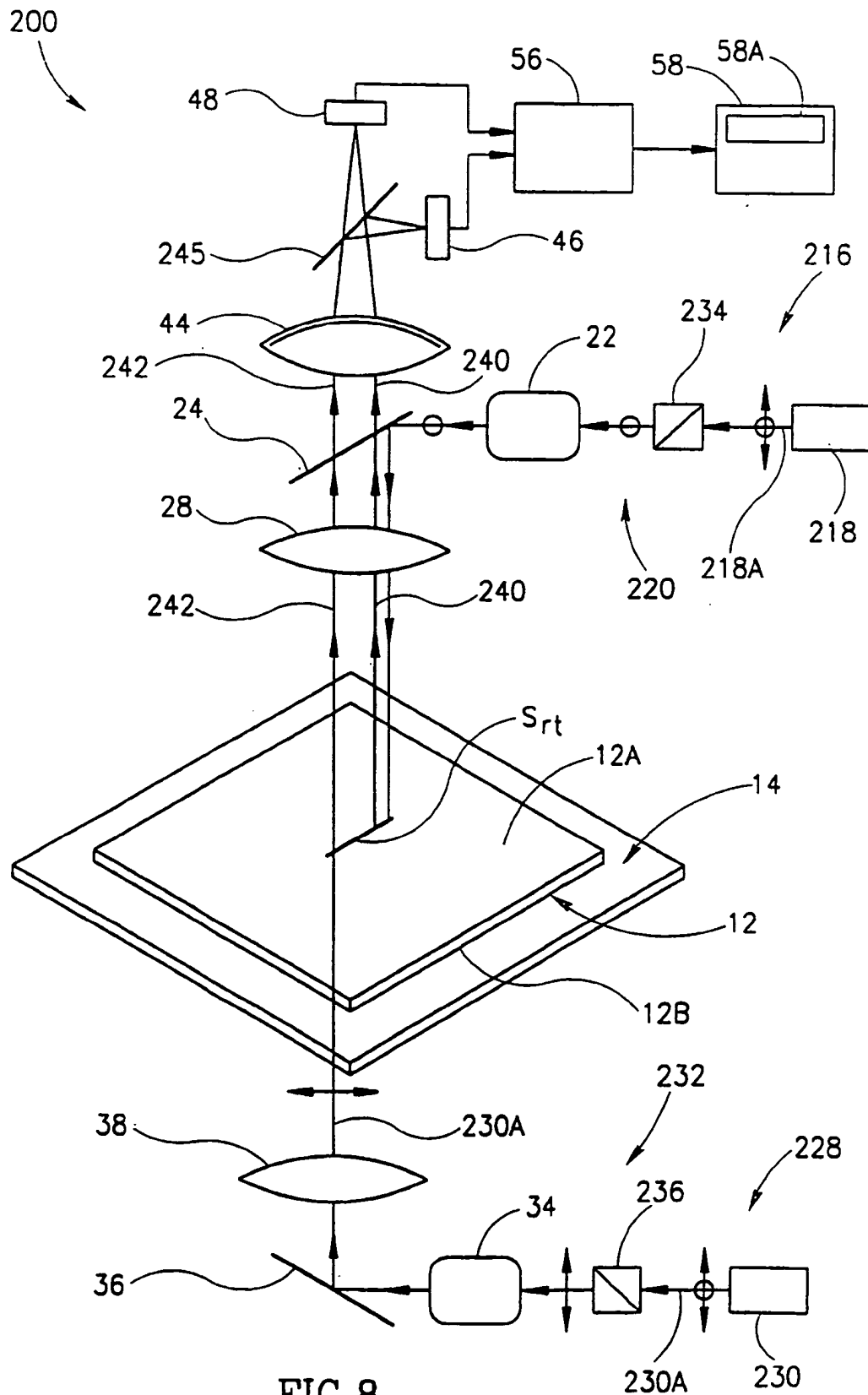


FIG. 7

7/7



INTERNATIONAL SEARCH REPORT

Internatic Application No
PCT/US 99/01107

A. CLASSIFICATION OF SUBJECT MATTER
IPC 6 G01N21/88

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 6 G01N 602B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 5 386 112 A (DIXON ARTHUR E) 31 January 1995 see column 5, line 43 - column 7, line 11; figure 4 ---	1, 3, 6-8, 11, 12, 14, 16, 17, 20, 22, 23
A	EP 0 819 933 A (ORBOT INSTR LIMITED) 21 January 1998 see column 3, line 31 - column 4, line 35 see column 5, line 50 - column 6, line 3; figures 1, 7 --- -/--	1, 7, 8, 10-17, 21-23



Further documents are listed in the continuation of box C.



Patent family members are listed in annex.

* Special categories of cited documents :

- *A* document defining the general state of the art which is not considered to be of particular relevance
- *E* earlier document but published on or after the international filing date
- *L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- *O* document referring to an oral disclosure, use, exhibition or other means
- *P* document published prior to the international filing date but later than the priority date claimed

T later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

X document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

Y document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

& document member of the same patent family

Date of the actual completion of the international search

6 May 1999

Date of mailing of the international search report

17/05/1999

Name and mailing address of the ISA

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

Scheu, M

INTERNATIONAL SEARCH REPORT

International application No

PCT/US 99/01107

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
P, X	<p>EP 0 838 679 A (NIPPON ELECTRIC CO) 29 April 1998</p> <p>see column 2, line 26 - line 37 see column 5, line 42 - column 8, line 14; figures 1,6</p> <p>-----</p>	<p>1,2,4,8, 11,14, 16,18, 20-23</p>

INTERNATIONAL SEARCH REPORT

Information on patent family members

Internat Application No

PCT/US 99/01107

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 5386112 A	31-01-1995	DE 69105977 D EP 0536273 A AT 115738 T CA 2086251 A WO 9200540 A	26-01-1995 14-04-1993 15-12-1994 30-12-1991 09-01-1992
EP 0819933 A	21-01-1998	JP 10123059 A US 5892579 A	15-05-1998 06-04-1999
EP 0838679 A	29-04-1998	JP 10185531 A	14-07-1998